

ERRATA for T. Shifrin's *Multivariable Mathematics: Linear Algebra,
Multivariable Calculus, and Manifolds*

p. 92, Example 7. The reference should be to Example 3 of Chapter 2, Section 3.

p. 155, Exercise 1. ... find a product of elementary matrices $E = \cdots E_2 E_1$ so that EA is in echelon form.

p. 188, Figure 5.2. The label should be $f(\mathbf{x}) = 0$.

p. 203, Definition. A critical point \mathbf{a} is a saddle point if for every $\delta > 0$, there are points $\mathbf{x}, \mathbf{y} \in B(\mathbf{a}, \delta)$ with $f(\mathbf{x}) < f(\mathbf{a})$ and $f(\mathbf{y}) > f(\mathbf{a})$.

p. 207, Exercise 2. The opposite corner should also be in the first octant, i.e., should have $x, y,$ and z all positive.

p. 256, line 6. Z is a neighborhood of $\begin{bmatrix} \mathbf{x}_0 \\ \mathbf{0} \end{bmatrix}$. In Figure 2.4, Z should be slid to the right, containing $V \times \{\mathbf{0}\}$.

p. 261, Exercise 13a. Suppose $f \begin{pmatrix} \mathbf{x}_0 \\ t_0 \end{pmatrix} = \frac{\partial f}{\partial t} \begin{pmatrix} \mathbf{x}_0 \\ t_0 \end{pmatrix} = 0$ and the matrix ... is nonsingular. Show that for some $\delta > 0$, there is a \mathcal{C}^1 curve $\mathbf{g}: (t_0 - \delta, t_0 + \delta) \rightarrow \mathbb{R}^2$ with $\mathbf{g}(t_0) = \mathbf{x}_0$ so that ...

p. 275, Exercise 10, line 5. ... requires at most volume $A\delta$.

p. 276, Exercise 14b. $D = \{\mathbf{x} \in R : f \text{ is discontinuous at } \mathbf{x}\}$.

p. 328, line 1. Section 3, not section 4.

p. 329, lines 13–15. In the long inequality we should have $\varepsilon \text{vol}(R)(1 + Mn)$ and $\varepsilon \text{vol}(R)(2^n + 2^{n-1}Mn)$. Then let $\beta = \text{vol}(R)(2^n + 2^{n-1}Mn)$.

p. 345, lines 4–5. We need the remark here that $\mathbf{g}_2^{-1} \circ \mathbf{g}_1$ is smooth. This can be proved by what should be an exercise in §6.3: Using the notation of part 3 of the Definition on p. 262 of a k -dimensional manifold, perhaps shrinking W , there is a smooth function $\mathbf{h}: W \rightarrow U$ whose restriction to $M \cap W$ is \mathbf{g}^{-1} . (Hint: Use the equivalent definition 1 to write $M \cap W$ as a graph over the $x_1 \cdots x_k$ -plane; write $\mathbf{g}(\mathbf{u}) = \begin{bmatrix} \mathbf{g}_1(\mathbf{u}) \\ \mathbf{g}_2(\mathbf{u}) \end{bmatrix} \in \mathbb{R}^k \times \mathbb{R}^{n-k}$, and note that \mathbf{g}_1 has a (local) smooth inverse.)

p. 352, add to Remark: Also, note that we are using the notation $\oint_C \omega$ to denote the integral of ω around the closed curve (or loop) C . This notation is prevalent in physics texts.

p. 355, lines –2 and –1. a should be \mathbf{a} .

p. 368–369, Example 2. In parts a and c, $D = (0, 1) \times (0, 2\pi)$.

p. 380, line 8. Add: “parametrization $g: U \rightarrow \mathbb{R}^n$ with $U \subset \mathbb{R}_+^k$ and”

p. 382, line 12. Delete the last equality in the displayed string of equations.

p. 410, lines 4 and 5. All the integrals should be over S^{2m} .

p. 411, Exercise 9. Suppose $U \subset \mathbb{C}$ is open, $f, g: U \rightarrow \mathbb{C}$ are smooth, and $C \subset U$ is a closed curve. Suppose that on C we have $f, g \neq 0$ and $|g - f| < |f|$. Prove that ...

p. 433, line 5. The 22 entry of $B - I$ should be 2.

p. 444, Example 7, line -3. $\dot{x}_1 = -x_2$.

p. 445, Example 8. Delete the first “the” in the first line.

p. 457, lines 11–12. “Let $W = (\text{Span}(\mathbf{v}_1))^\perp \subset \mathbb{R}^n$ ” should precede the second sentence of the paragraph.

p. 480, #4.5.11a. $DF(\mathbf{x})$ has rank 2 at every point $\mathbf{x} \in M$: Either $x_1 = x_2$ and $x_3 = -x_4$ or $x_1 = -x_2$ and $x_3 = x_4$, so x_1x_2 and x_3x_4 have opposite signs unless they are both 0.

p. 482, #6.2.1: $Dg(\mathbf{f}(\mathbf{x}_0)) = \frac{1}{2(x_0^2 + y_0^2)} \cdots$

p. 483, #7.3.12: The picture is not correct.

