

Review

4.3 #16

$$\dim V^\perp = n - \dim V$$

$$4 - 2 = 2$$

let $V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right\}$ in \mathbb{R}^4

set $T = \text{Proj}_V$

find standard matrix of T

Plan: (for this section)

- 1) find convenient basis \mathcal{B} for \mathbb{R}^4
- 2) find $[T]_{\mathcal{B}}$
- 3) use change of basis formula

1) pick $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix}$

$T\vec{v}_1 = \vec{v}_1$ $T\vec{v}_2 = \vec{v}_2$

\vec{v}_3, \vec{v}_4 they are in V^\perp we know what proj. onto V does to them

$\vec{v}_3 = \begin{bmatrix} \dots \\ \dots \\ \dots \\ \dots \end{bmatrix}$ $\vec{v}_4 = \begin{bmatrix} \dots \\ \dots \\ \dots \\ \dots \end{bmatrix}$

} orthogonal to V

to find \vec{v}_3, \vec{v}_4 consider $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \perp V$

$$\Leftrightarrow x_1 + 2x_3 + x_4 = 0$$

$$x_2 - x_3 + x_4 = 0$$

$$\begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -1 & 1 \end{bmatrix} \quad \begin{aligned} x_1 &= -2x_3 - x_4 \\ x_2 &= x_3 - x_4 \end{aligned}$$

$$x_3 = x_3$$

$$x_4 = x_4$$

so $\vec{v}_3 = \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \end{bmatrix}$ $\vec{v}_4 = \begin{bmatrix} -1 \\ -1 \\ 0 \\ 1 \end{bmatrix}$

$T\vec{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ $T\vec{v}_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

orthogonal complement is span of \vec{v}_3 & \vec{v}_4

do T to 1st basis vector
express $T\vec{v}_1$ as linear combination of other vectors

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 0 & -2 & -1 \\ 0 & 1 & 1 & -1 \\ 2 & -1 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix}$$

$$P[T]_{\mathcal{B}} = [T]_{\text{STD}} P$$

$$[T]_{\text{STD}} = P[T]_{\mathcal{B}} P^{-1}$$

To find $[Proj_V]_{\text{STD}}$ \rightsquigarrow many diff ways

Construct a matrix A whose column space is V

$$A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 2 & -1 \\ 1 & 1 \end{bmatrix}$$

$$[proj_{\text{col}(A)}]_{\text{STD}} = A(A^T A)^{-1} A^T$$

where comes from

Solve equation $A\vec{x} = \vec{b}$ which usually does not have a solution so...
consider $A^T A \vec{x} = A^T \vec{b}$ which always has a solution

$$\Leftrightarrow A\vec{x} = proj_{\text{col}(A)} \vec{b}$$

Find an orthogonal basis for V

take $\vec{w}_1 = \vec{v}_1$
 $\vec{w}_2 = \vec{v}_2 - \frac{\vec{v}_2 \cdot \vec{v}_1}{\|\vec{v}_1\|^2} \vec{v}_1$

part of \vec{v}_2 orthogonal to \vec{v}_1

$$= \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} - \frac{-1}{6} \begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1/6 \\ 0 \\ -1/6 \\ 1/6 \end{bmatrix} = \begin{bmatrix} 1/6 \\ 1 \\ -2/3 \\ 7/6 \end{bmatrix}$$

would be nice to avoid fractions,
so can use a scalar multiple of $\vec{w}_2 \rightarrow$ replace with

$$6 \begin{bmatrix} 1/6 \\ 1 \\ -2/3 \\ 7/6 \end{bmatrix}$$

new basis for V : $\left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -6 \\ -4 \\ 7 \end{bmatrix} \right\}$ orthogonal basis for V

$$\begin{aligned} \text{find } \text{proj}_V \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} &= \text{proj}_{\begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \text{proj}_{\begin{bmatrix} 1 \\ -6 \\ -4 \\ 7 \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \\ &= \frac{x_1 + 2x_3 + x_4}{6} \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix} + \frac{x_1 + 6x_2 - 4x_3 + 7x_4}{102} \begin{bmatrix} 1 \\ -6 \\ -4 \\ 7 \end{bmatrix} \end{aligned}$$

$$[\text{Proj}_V]_{\text{STD}} = \left[\text{Proj} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \dots, \text{Proj} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right]$$

$$\text{Proj}_V \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix} + \frac{1}{102} \begin{bmatrix} 1 \\ -6 \\ -4 \\ 7 \end{bmatrix}$$

$$V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -6 \\ -4 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

b/c this is 3 dim
easy to use V^\perp b/c 1 dim

take $T = \text{proj}_V$
find $[T]_{\text{STD}}$

① Find a basis for V^\perp \rightarrow let vectors be rows of A
then

$$\begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix} \quad \begin{aligned} x_1 &= 3x_4 \\ x_2 &= -3x_4 \\ x_3 &= -2x_4 \\ x_4 &= x_4 \end{aligned}$$

basis for V^\perp $\begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix}$

$$\text{Proj}_{V^\perp} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \frac{\begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}}{\begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix}} \begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix} = \frac{3x_1 - 3x_2 - 2x_3 + x_4}{23} \begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix}$$

4

$$\text{proj}_V \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} - \frac{3x_1 - 3x_2 - 2x_3 + x_4}{23} \begin{bmatrix} 3 \\ -3 \\ -2 \\ 1 \end{bmatrix}$$

$$[\text{Proj}_V]_{\text{STD}} = \begin{bmatrix} 9/23 & & & \\ & -9/23 & & \\ & & -4/23 & \\ & & & 3/23 \end{bmatrix}$$

see what transformation
(proj_V) does to:
 $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$

$$[\text{Proj}_V]_{\text{STD}} = I - [\text{Proj}_{V^\perp}]_{\text{STD}}$$

$$\text{b/c } \text{Proj}_V + \text{Proj}_{V^\perp} = I$$

Given:

$$\mathcal{B}: \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

find the standard matrix of T

$$P = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$$[T]_{\text{STD}} P = P [T]_{\mathcal{B}}$$

$$[T]_{\text{STD}} = P [T]_{\mathcal{B}} P^{-1}$$

what does it mean $[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$

$$\text{by defn: } \begin{aligned} T\vec{v}_1 &= \vec{v}_1 + \vec{v}_2 \\ T\vec{v}_2 &= \vec{v}_1 \end{aligned}$$

$$\begin{aligned} T \begin{bmatrix} 1 \\ 1 \end{bmatrix} &= \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\ T \begin{bmatrix} 1 \\ 2 \end{bmatrix} &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

$$\text{set } A = [T]_{\text{STD}}$$

$$\text{then } A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \quad \text{and} \quad A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 3 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}^{-1}$$

Find the parabola $y = ax^2$ (*) which comes closest to passing through the points $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$

really want: $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ to satisfy (*)

$$1 = a$$

also want $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$ to satisfy (*)

$$3 = 4a$$

$$\underbrace{\begin{bmatrix} 1 \\ 4 \end{bmatrix}}_A \underbrace{\begin{bmatrix} a \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} 1 \\ 3 \end{bmatrix}}_{\vec{b}} \quad \} \text{ inconsistent}$$

for the least squares solution we solve

$$A^T A \vec{x} = A^T \vec{b}$$

$$\begin{bmatrix} 1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} x = \begin{bmatrix} 1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$17x = 13$$

$$x = \frac{13}{17}$$

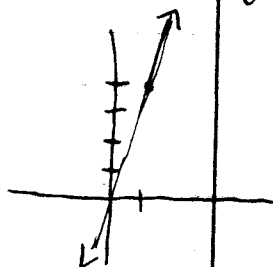
$$\hookrightarrow a = \frac{13}{17}$$

\therefore best parabola is $y = \frac{13}{17} x^2$

In text

$$\begin{aligned}
 (*) \text{reflec}_v &= \text{proj}_v - \text{proj}_{v^\perp} \\
 &= \text{proj}_v - (I - \text{proj}_v) \\
 &= 2 \text{proj}_v - I
 \end{aligned}$$

let $T =$ reflection about line $y = 4x$
 find $[T]_{\text{STD}}$



① Find the formula for $(\text{proj}_v)\begin{bmatrix} x \\ y \end{bmatrix} = \text{proj}_{\begin{bmatrix} 1 \\ 4 \end{bmatrix}} \begin{bmatrix} x \\ y \end{bmatrix} =$

$$\frac{x+4y}{17} \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

what happens to $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$[\text{Proj}_v]_{\text{STD}} = \begin{bmatrix} 1/17 & 4/17 \\ 4/17 & 16/17 \end{bmatrix}$$

if you square matrix should get same matrix
 v/c projecting 2x gives same vector

by (*)

$$[\text{reflec}_v]_{\text{STD}} = \begin{bmatrix} 2/17 & 8/17 \\ 8/17 & 32/17 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

when you reflect 2x you get back where u started from so matrix² = I

other plan:

choose convenient basis :

we know $T \begin{bmatrix} 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$
 $T \begin{bmatrix} -4 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$

orthogonal to $\begin{bmatrix} 1 \\ 4 \end{bmatrix}$

$$P [T]_{\mathcal{B}} = [T]_{\text{STD}} P$$

$$[T]_{\text{STD}} = P \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} P^{-1}$$

pick basis $\begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \end{bmatrix}$ $[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ $P = \begin{bmatrix} 1 & -4 \\ 4 & 1 \end{bmatrix}$

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k$ are orthogonal if $\vec{x}_i \cdot \vec{x}_j = 0$ for $i \neq j$

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k$ are orthonormal if in addition each vector is a unit vector (has length $(\|\vec{x}_i\|) = 1$)

Good things about orthogonal bases

① It's easy to find coordinates relative to them

Ex.

$\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ ← orthogonal basis for \mathbb{R}^2

express $\begin{bmatrix} 5 \\ 17 \end{bmatrix}$ as a linear combination of these vectors.

which means we want: $\begin{bmatrix} 5 \\ 17 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

dot with $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 17 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 \underbrace{\begin{bmatrix} 2 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}}_{\text{zero}}$$

$$39 = 5c_1$$

$$c_1 = 39/5$$

now dot with $\begin{bmatrix} 2 \\ -1 \end{bmatrix}$

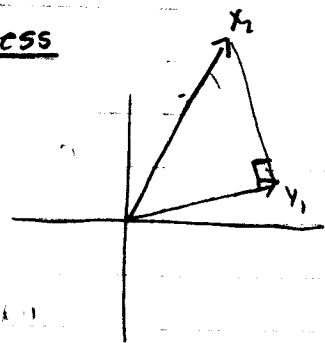
$$-7 = 5c_2$$

$$c_2 = -7/5$$

How do you find them? → Gram-Schmidt Process

start with $\vec{x}_1, \vec{x}_2, \vec{x}_3$ independent

find a new set of vectors.



orthogonal same span as x_1, x_2, x_3

$$\vec{y}_1 = \vec{x}_1$$

$$\vec{y}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{y}_1}{\|\vec{y}_1\|^2} \vec{y}_1$$

proj onto y_1

so you are left w/ proj orthogonal to y_1

$$\vec{y}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{y}_1}{\|\vec{y}_1\|^2} \vec{y}_1 - \frac{\vec{x}_3 \cdot \vec{y}_2}{\|\vec{y}_2\|^2} \vec{y}_2$$

①

show

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 2 & 2 \end{bmatrix}$$

is similar to a diagonal matrix.

has basis of
eigenvectors② find A^{100}

① find the eigenvalues

$$\det(A - tI) = \det \begin{bmatrix} -t & 0 & 0 \\ 0 & 2-t & 2 \\ 0 & 2 & 2-t \end{bmatrix} =$$

$$(-t) \det \begin{bmatrix} 2-t & 2 \\ 2 & 2-t \end{bmatrix} =$$

$$(-t) [4 - 4t + t^2 - 4] =$$

$$(-t) (t^2 - 4t) =$$

$$(-t)(t)(t-4) = 0$$

$$t=0, t=4 \} \text{ eigenvalues}$$

find the eigenvectors: (basis for each eigenspace)

for $t=4$

$$A - 4I = \begin{bmatrix} -4 & 0 & 0 \\ 0 & -2 & 2 \\ 0 & 2 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} x_1 &= 0 \\ x_2 &= x_3 \\ x_3 &= x_3 \end{aligned}$$

$$\text{basis for } E_4 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

one free variable
hence 1 basis
vectorfor $t=0$

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 2 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} x_1 &= x_1 \\ x_2 &= -x_3 \\ x_3 &= x_3 \end{aligned}$$

2 free
variable
hence 2
basis
vectors

$$\text{basis for } E_0 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix} \quad P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$AP = PD$$

$$A = P \begin{bmatrix} 0 & & \\ & 0 & \\ & & 4 \end{bmatrix} P^{-1}$$

$$A^{100} = P \begin{bmatrix} 0 & & \\ & 0 & \\ & & 4^{100} \end{bmatrix} P^{-1}$$

can leave like this unless you need it for something

don't worry about kernel & image

↓
N(A)

↓
C(A)

suppose $A^T = I$

$$\det A^2 = \det I$$

$$(\det A)^2 = 1$$

$$x^2 = 1$$

$$x = \pm 1$$

$A^T A = I$ (orthogonal matrix)

$$\det(A^T A) = \det I$$

$$(\det A^T)(\det A) = 1$$

$$(\det A)(\det A) = 1$$

$$(\det A)^2 = 1$$

$$\det A = \pm 1$$

matrices of rotations & reflections are orthogonal matrices they preserve length

Prop: TFAE:

$$(1) A^T A = I$$

$$(2) \|Ax\| = \|x\| \text{ for every vector } x$$

PF:

$$\|Ax\|^2 = (Ax) \cdot (Ax) = (Ax)^T (Ax) = x^T A^T A x = x^T x = x \cdot x = \|x\|^2$$

proofs w/ eigenvalues & eigenvectors
w/ similarity
w/ subspaces & independence

similar matrices

$A, B \in M_n$ are similar if there is an invertible matrix P such that $P^{-1}AP = B$ ($AP = PB$)

properties:

(1) $[T]_{\mathcal{B}}$ is similar to $[T]_{\mathcal{S}}$

(2) a matrix A is diagonalizable IFF A is similar to a diagonal matrix IFF \exists basis of eigenvectors for A

remember:

A similar to $B \stackrel{?}{\implies} A^2$ similar to B^2

Proof: find invertible P with

$$AP = PB$$

$$A^2P = A(AP) = A(PB) = (AP)(B) = P(BB) = PB^2$$

or

$$P^{-1}AP = B$$

$$(P^{-1}AP)^2 = B^2$$

$$(P^{-1}AP)(P^{-1}AP) = B^2$$

$$P^{-1}A^2P = B^2$$

\therefore statement true

all proj
onto 1 dim
space r
similar to
one another

A^2 similar to $B^2 \stackrel{?}{\Rightarrow} A$ similar to B .

NO: $A = [1]$ $B = [-1]$

not similar, but $A^2 \text{ even} = B^2$

if something is similar to I then has to be I

To show A, B are similar:

1) find a linear transformation T with $[T]_{STD} = A$
and $[T]_B = B$

2) solve $AP = PB$ for invertible P

will
not
have
to
do

To show A, B are NOT similar:

1) show that they have different eigenvalues

2) show the eigenspaces have different dimensions

all continuous functions

Ex.

$$\textcircled{1} V = \{ f \in C(\mathbb{R}) \mid f(3) = 1 \}$$

not a subspace because $\vec{0}$ is not include

$$\textcircled{2} V = \{ f \in C(\mathbb{R}) \mid f(3) = 0 \}$$

Yes this is a subspace

(1) $0 \in V$ \rightarrow so when you apply zero function to 3 do you get zero \rightarrow yes!(2) suppose $f, g \in V$

$$\text{then } (f+g)(3) = f(3) + g(3) = 0 + 0 = 0$$

 $\therefore V$ is closed under addition(3) suppose $f \in V$ and $c \in \mathbb{R}$

$$(cf)(3) = c(f(3)) = c(0) = 0$$

 $\therefore cf \in V \therefore V$ is closed under scalar multiplication

$$\textcircled{3} V = \{ f \in C(\mathbb{R}) \mid f(3) \geq 0 \}$$

1) $0 \in V$

2) closed under addition

3) $f(x) = x$ (belongs to V)

$$-1(f(x)) = -x$$

$$(-f)(3) = -3$$

not a subspace \because not closed under scalar multiplication

polynomials of degree ≤ 2

$$(4) \quad V = \{ p \in P_2 \mid p(3) = 0 \}$$

$$P_2 = \{ \text{all polynomials of deg} \leq 2 \}$$

basis for P_2 :

$$P_1(x) = 1$$

$$P_2(x) = x$$

$$P_3(x) = x^2$$

clearly, they span

suppose $c_1(1) + c_2x + c_3x^2 = 0$ for all x

in particular, true $x=0$

$$\text{then } c_1 = 0$$

$$\text{so } c_2x + c_3x^2 = 0 \quad \forall x$$

$$x = -1$$

$$-c_2 + c_3 = 0$$

$$x = 1$$

$$c_2 + c_3 = 0$$

$$\left. \begin{array}{l} -c_2 + c_3 = 0 \\ c_2 + c_3 = 0 \end{array} \right\} \text{force } c_2 = c_3 = 0$$

since $c_1 = c_2 = c_3 = 0$, vectors are independent

$$\dim P_2 = 3$$

b/c # vectors needed to make basis for vector space = dim

what is the most general member of P^2 ?

$$p(x) = ax^2 + bx + c$$

when is $p \in V$?

$$\Leftrightarrow p(3) = 0$$

$$\Leftrightarrow 9a + 3b + c = 0$$

$$\Leftrightarrow c = -9a - 3b$$

most general member of V : $p(x) = ax^2 + bx - 9a - 3b$
 $= a(x^2 - 9) + b(x - 3)$

basis for V :

$$p_1(x) = x^2 - 9$$

$$p_2(x) = x - 3$$

clearly they span

✓ if independent

suppose $c_1(x^2 - 9) + c_2(x - 3) \equiv 0$ for all x

take $x = -3$

$$c_2(-6) = 0 \Rightarrow c_2 = 0$$

now have $c_1(x^2 - 9) = 0$

take $x = 0$

$$c_1(-9) = 0 \Rightarrow c_1 = 0$$

or

$$c_1 x^2 + c_2 x + (-9c_1 - 3c_2)(1) = 0$$

we know these are indep

∴ indep ∴ basis

$$\dim V = 2$$

40,000 girls in a class

$\frac{3}{4}$ of the girls who color their hair one day also color it the next day

$\frac{1}{5}$ of the girls who go natural one day color their hair the next day

everyone goes natural the zeroth day

- 1) How many girls have colored their hair on day n ?
- 2) find the equilibrium #
- 3) do you always approach this equilibrium?

x_n = # with colored hair on day n

y_n = # with natural hair on day n

$$x_{n+1} = \frac{3}{4}x_n + \frac{1}{5}y_n$$

$$y_{n+1} = \frac{1}{4}x_n + \frac{4}{5}y_n$$

$$\begin{bmatrix} x_{n+1} \\ y_{n+1} \end{bmatrix} = \begin{bmatrix} \frac{3}{4} & \frac{1}{5} \\ \frac{1}{4} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} x_n \\ y_n \end{bmatrix}$$

A

1) diagonalize A

$$\begin{aligned} \det(A - tI) &= \left(\left(\frac{3}{4} - t \right) \left(\frac{4}{5} - t \right) \right) - \frac{1}{20} \\ &= t^2 - \frac{31}{20}t + \frac{11}{20} \\ &= (t-1) \left(t + \frac{1}{20} \right) \end{aligned}$$

eigenvalue | eigenvector

1	$\begin{bmatrix} 4 \\ 3 \\ -1 \end{bmatrix}$
$\frac{1}{20}$	$\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$

$$A - \frac{1}{20}I =$$

$$\begin{bmatrix} \frac{1}{5} & \frac{1}{5} \\ \frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

$$D = \begin{bmatrix} 1 & 0 \\ 0 & 1/20 \end{bmatrix}$$

$$P = \begin{bmatrix} 4 & 1 \\ 5 & -1 \end{bmatrix}$$

$$AP = PD$$

$$A = P \begin{bmatrix} 1 & 0 \\ 0 & 1/20 \end{bmatrix} P^{-1}$$

on day n , $\begin{bmatrix} x_n \\ y_n \end{bmatrix} = A^n \begin{bmatrix} 0 \\ 40,000 \end{bmatrix} = P \begin{bmatrix} 1 & 0 \\ 0 & 1/20 \end{bmatrix}^n P^{-1} \begin{bmatrix} 0 \\ 40,000 \end{bmatrix}$

equilib.

2) $\begin{bmatrix} x_\infty \\ y_\infty \end{bmatrix}$ must be an eigenvector corresponding to eigenvalue $\lambda = 1$

$$\begin{bmatrix} x_\infty \\ y_\infty \end{bmatrix} \text{ must be some } c \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$

$$x_\infty + y_\infty = 40,000$$

$$4c + 5c = 40,000 \Rightarrow 9c = 40,000$$

$$c = \frac{40,000}{9}$$

$$4c = \frac{160,000}{9} \approx 20,000 \text{ have hair dyed}$$

3) $\lim_{n \rightarrow \infty} \begin{bmatrix} x_n \\ y_n \end{bmatrix} = P \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} P^{-1} \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} = \underbrace{\begin{bmatrix} 4/9 & 7/9 \\ 5/9 & 5/9 \end{bmatrix}}_{\text{Azoll did for vs}} \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} =$

$$\begin{bmatrix} 4/9 (x_0 + y_0) \\ 5/9 (x_0 + y_0) \end{bmatrix} = \begin{bmatrix} 4/9 (40,000) \\ 5/9 (40,000) \end{bmatrix} \leftarrow \begin{array}{l} \text{same \# as} \\ \text{equilib \#} \end{array}$$

$$\begin{array}{l} x_0 + y_0 = \\ 40,000 \end{array}$$

so no matter starting numbers, would have same equilibrium.

continuous
1st derivative cont,
2nd derivative cont,

$$V = \{ f \in C^2(\mathbb{R}) \mid f'' - f' - 6f = 0 \}$$

is V a subspace? YES

1) $0 \in V$

2) suppose $f, g \in V$

$$\begin{aligned} \text{consider } (f+g)'' - (f+g)' - 6(f+g) &= \\ f'' + g'' - f' - g' - 6f - 6g &= \\ (f'' - f' - 6f) + (g'' - g' - 6g) &= \\ 0 + 0 = 0 &\quad \therefore f+g \in V \end{aligned}$$

$\therefore V$ is closed under addition

3) suppose $f \in V$ and $c \in \mathbb{R}$

$$\begin{aligned} \text{consider } (cf)'' - (cf)' - 6(cf) &= \\ c(f'' - f' - 6f) &= 0 \end{aligned}$$

Fact: V is 2 dimensional

Find a basis: *wouldn't be that hard*

try $f(x) = e^{rx}$
 want $f'' - f' - 6f = 0$

$$r^2 e^{rx} - r e^{rx} - 6 e^{rx} = (r^2 - r - 6) e^{rx}$$

$\underbrace{\hspace{10em}}_{\text{never zero}}$

$$\begin{aligned} \text{so } r^2 - r - 6 &= 0 \\ (r-3)(r+2) &= 0 \\ r &= 3, r = -2 \end{aligned}$$

$$\begin{aligned} b_1(x) &= e^{3x} \\ b_2(x) &= e^{-2x} \end{aligned}$$

V if they are independent

suppose $c_1 e^{3x} + c_2 e^{-2x} \equiv 0$
 $x = 0$

$$c_1 + c_2 = 0$$

$$\begin{aligned} c_1 3e^{3x} + c_2 (-2)(e^{-2x}) &= 0 \text{ if } x=0 \\ 3c_1 - 2c_2 = 0 &\implies c_1 = c_2 = 0 \end{aligned}$$

if 2 things are always = then their derivatives are equal