

September 24, 2009

Review for Test #1

$\|c\vec{x}\| = |c| \|\vec{x}\|$

$\vec{x} = \begin{bmatrix} 5 \\ 8 \end{bmatrix} \quad \|\vec{x}\| = \sqrt{5^2 + 8^2} = \sqrt{89}$

$\frac{1}{\sqrt{89}} \begin{bmatrix} 5 \\ 8 \end{bmatrix} = \begin{bmatrix} 5/\sqrt{89} \\ 8/\sqrt{89} \end{bmatrix} \quad \|\vec{y}\| = \sqrt{(5/\sqrt{89})^2 + (8/\sqrt{89})^2}$

Given  $\begin{cases} \vec{v} \text{ (on line } l) \\ \vec{y} \end{cases}$

$\begin{cases} \text{Find the distance between a point and a} \\ \text{line} \end{cases}$

$\vec{y} = \vec{y}_{\parallel} + \vec{y}_{\perp}$  where  $\begin{cases} \vec{y}_{\parallel} \parallel \vec{v} \\ \vec{y}_{\perp} \perp \vec{v} \end{cases}$

proj of  $\vec{y}$  on  $l$       proj of  $\vec{y}$  orthogonal to  $l$

\*orthogonal in front of projection does not mean anything.

Section 1.3 in Text: Hyperplane in  $\mathbb{R}^n$

Given  $\vec{v} \in \mathbb{R}^n \quad v \neq \vec{0} \quad \vec{v} = (v_1, \dots, v_n)$   
 $b \in \mathbb{R}$

The corresponding hyperplane is  $\mathbb{H} = \left\{ \vec{x} \in \mathbb{R}^n \mid \vec{v} \cdot \vec{x} = b \right\}$   
 $\left\{ \vec{x} \in \mathbb{R}^n \mid v_1 x_1 + \dots + v_n x_n = b \right\}$

Example ①  $n=2 \quad b=0 \quad \vec{v}=(1,2)$   
 $H = \left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2 \mid x_1 + 2x_2 = 0 \right\}$   
 (line through the origin)

②  $n=2 \quad b=5 \quad \vec{v}=(1,2)$   
 $H = \left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2 \mid x_1 + 2x_2 = 5 \right\}$   
 line  $\parallel$  ① 1-Dimension

③  $n=3 \quad b=0 \quad \vec{v}=(1,2,3)$   
 $H = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 + 3x_3 = 0 \right\}$  In  $\mathbb{R}^3 = 2D$  or  $1D$   
 Plane (2-Dimension) in  $\mathbb{R}^3$

Hyperplane is a solution to a single equation. It's one dimension less.  
 THAN THE AMBIENT SPACE  $\mathbb{R}^n$ .

9/24/09

Descriptions of a space

(1) Parametric

(2) Cartesian = Constraint = Intersections of Hyperplanes.

Defn: The rank of a matrix is the number of pivots in its echelon form. Classify solution types of

$$A\vec{x} = \vec{b} \quad (A, \vec{b}) \text{ Fixed}$$

1) Unique  $\Leftrightarrow \text{Rank } A = \text{Rank}[A|\vec{b}] = m$

2) No solutions  $\Leftrightarrow \text{Rank } A < \text{Rank}[A|\vec{b}]$

3)  $\infty$ -ly many solutions  $\Leftrightarrow \text{Rank } A = \text{Rank}[A|\vec{b}] < n$

The Rank of the augmented matrix EITHER EQUALS RANK  $A$  OR EQUALS  $1 + \text{Rank } A$ .

$A_{m \times n}$  Given

Characteristics of Solutions to  $A\vec{x} = \vec{b}$  for different  $\vec{b}$ 's

1) Unique solution for every  $\vec{b}$ . THIS HAPPENS IF AND ONLY IF  $A \rightarrow I$  ( $A$  REDUCES TO  $I$ )

$\Leftrightarrow$  Pivot in every row and a pivot in every column of  $A$ .

$\Leftrightarrow R = m = n$ .

\* Only time you can always have a unique solution is when Matrix is square.

2)  $R = m < n$   $A\vec{x} = \vec{b}$  always have infinitely many solutions.

3)  $R = n < m$  unique for some  $\vec{b}$  and no solution for other  $\vec{b}$ 's.

$$\vec{x} = \vec{a} + t\vec{v}$$
$$\sum_i t_i \vec{v}_i \quad t_i \in \mathbb{R}$$

$$\begin{bmatrix} 2 & 1 & 3 \\ 0 & 5 & 3 \end{bmatrix}$$

IF FREE VARIABLES.

Rank = # pivots in echelon form.

Free variables is columns that don't have pivots.

SEVERAL

• Linear Combinations: The sum of scalar multipliers of  $n$  vectors.

• Angle between vectors  $\theta = \cos^{-1} \left( \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \right)$

• Echelon: The leading non zeros in later rows are to the right of the rows previous.

• Singular, non-singular refer to square matrices.

• Matrix is its own transpose  $\Leftrightarrow$  Symmetric.