
Phase Plane Analysis

Lecture 7

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General 2-d models

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$$\dot{y} = g(x, y)$$

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 - ▷ Identify the stable/unstable manifolds

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- ◇ Establish stability of fixed points
 - ▷ Establish the nature of the fixed points
 - ▷ Identify the stable/unstable manifolds
- ◇ Draw nullclines

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Theorem: Linear stability implies non-linear stability if none of the eigen values have zero real parts.

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Easy rule: Eigen values of a 2x2 matrix A have negative real parts if and only if the determinant of A is positive and the trace of A is negative.

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Note that the **eigen values** are:

$$\lambda_{1,2} = \frac{\operatorname{tr} A}{2} \pm \frac{1}{2} \sqrt{(\operatorname{tr} A)^2 - 4 \det A}$$

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- ◇ **Spirals or vortices** can be unstable or stable but have two complex eigenvalues with both positive or both negative real parts and occur when $D < 0$. Solutions spiral into or out of these fixed points.
- ◇ **Saddles** consist of one positive and one negative eigenvalue. They are unstable and occur when $D < 0$.

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- ◇ Consider the **positive eigenvalue**. Associated with this is the corresponding eigenvector. There exists a pair of solutions which leave the fixed point tangent to this eigenvector, and these are called the **unstable manifold**.
- ◇ Consider the **negative eigenvalue**. Similarly, there is a unique pair of solutions which come into the fixed point tangent to the eigenvector associated with the negative eigen value, called the **stable manifold**.

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- ◇ Note that $\dot{x} = f(x, y)$, so if $f(x, y) > 0$ then x is increasing, which in turn means that it is moving rightward in the phase-plane.
- ◇ y – *nullcline* is the set of points where $g(x, y) = 0$.
- ◇ Intersections of nullclines are places where $f(x, y) = 0 = g(x, y)$. These are fixed points!