

MATH 4250/6250

Problem set 13, due 4/24

Solutions

✓A. Show class + textbook descriptions of the trajectory are equivalent.

Class: $h = Ae^{aw}$, $g = \pm \int_0^w \sqrt{1 - a^2 A^2 e^{2at}} dt + D$

$$\frac{dg}{dw} = \pm \sqrt{1 - a^2 A^2 e^{2aw}}$$

$$\left(\frac{dg}{dw}\right)^2 = 1 - a^2 A^2 e^{2aw}, \quad \frac{dh}{dw} = a A e^{aw} \quad \left(\frac{dh}{dw}\right)^2 = a^2 A^2 e^{2aw}$$

$$\left(\frac{dg}{dw}\right)^2 + \left(\frac{dh}{dw}\right)^2 = 1$$

Text: $g = u$, $\frac{dh}{du} = \frac{-h}{\sqrt{1-h^2}}$

$$\frac{dh}{du} = \frac{dh}{dw} \frac{dw}{du}$$

$$\left(\frac{dh}{du}\right)^2 = \frac{\left(\frac{dh}{dw}\right)^2}{\left(\frac{dw}{du}\right)^2}$$

$$= \frac{\left(\frac{dh}{dw}\right)^2}{1 - \left(\frac{dh}{dw}\right)^2}$$

$$= \frac{a^2 A^2 e^{2aw}}{1 - a^2 A^2 e^{2aw}}$$

$$= \frac{a^2 h^2}{1 - a^2 h^2} = \frac{h^2}{\frac{1}{a^2} - h^2}$$

$$= \frac{h^2}{c^2 - h^2} \quad \boxed{c = \frac{1}{a}}$$

$$h = \pm \frac{h}{\sqrt{c^2 - h^2}}$$

$$h = - \frac{h}{\sqrt{c^2 - h^2}} \quad \checkmark$$

B. Oprea : (5.1.1) (5.1.2) (5.1.3) (5.1.9) (5.1.10) (5.1.12) (5.1.1)

(5.1.1) Show $\kappa_a^2 = k(\vec{a}')^2 + \kappa_g^2$

\vec{a} unit speed $\Rightarrow \vec{a}'' = \kappa_a \vec{N}$ (defn. of κ_a and \vec{N})

$\kappa_a \vec{N} \perp T \Rightarrow \kappa_a \vec{N} = a \vec{U} + b \vec{U} \times \vec{T}$

$\kappa_g \stackrel{\text{def}}{=} \vec{a}'' \cdot \vec{U} \times \vec{T} \Rightarrow b = \kappa_g$

$k(\vec{a}') \stackrel{\text{def}}{=} S(\vec{a}'), \vec{a}' = \vec{U} \cdot \vec{a}'' \Rightarrow a = k(\vec{a}'')$

$\boxed{\kappa_a \vec{N} = k(\vec{a}'') \vec{U} + \kappa_g \vec{U} \times \vec{T}}$ dot each side w. ~~it~~ itself

$\kappa_a^2 = (k(\vec{a}''))^2 + (\kappa_g)^2 \checkmark$

(5.1.2) $\vec{X}(u,v) = ((R+r \cos u) \cos v, (R+r \cos u) \sin v, r \sin u)$

$\vec{U} = -(\cos u \cos v, \cos u \sin v, \sin u)$

top curve : $u = \frac{\pi}{2}, \cos u = 0, \sin u = 1$

$\vec{a}(t) = (R \cos t, R \sin t, r)$

$\vec{a}'(t) = (-R \sin t, R \cos t, 0) \quad |\vec{a}'(t)| = R$

$\vec{a}(s) = (R \cos \frac{s}{R}, R \sin \frac{s}{R}, r)$

$\vec{T} = (-\sin \frac{s}{R}, \cos \frac{s}{R}, 0)$

$\frac{d\vec{T}}{ds} = (-\frac{1}{R} \cos \frac{s}{R}, -\frac{1}{R} \sin \frac{s}{R}, 0) = \kappa \vec{N}$

$\kappa = \frac{1}{R}, \vec{N} = (\cos \frac{s}{R}, \sin \frac{s}{R}, 0)$

$$\begin{aligned}\vec{u} &= (-\cos u \cos v, -\cos u \sin v, \sin u) \\ &= (0, 0, 1) \\ \vec{T} &= (-\sin t, \cos t, 0)\end{aligned}$$

$$\vec{u} \times \vec{T} = (-\cos t, -\sin t, 0)$$

$$\kappa \vec{N} \cdot \vec{u} \times \vec{T} = \frac{1}{R} (-\cos t, -\sin t, 0) \cdot (-\cos t, -\sin t, 0)$$

$$\kappa_g = \frac{1}{R}$$

$$\kappa \vec{N} \cdot \vec{u} = (-\cos t, -\sin t, 0) \cdot (0, 0, 1) = 0 \Rightarrow \kappa(\vec{\alpha}) = 0$$

$$\begin{aligned}\kappa^2 &= \kappa(\vec{\alpha})^2 + (\kappa_g)^2 \\ \left(\frac{1}{R}\right)^2 &= 0^2 + \left(\frac{1}{R}\right)^2 \quad \checkmark\end{aligned}$$

(5.1.3) $\vec{\alpha}(s)$ unit speed curve on M , $\vec{\alpha}'(0) = \vec{0}$.

$$\vec{\beta}(s) = \vec{\alpha}(s) + \rho(s) \vec{u}_0$$

$$\vec{\beta}(s) = \vec{\alpha}(s) - (\vec{\alpha}(s) \cdot \vec{u}_0) \vec{u}_0 \quad \text{show } \kappa_g(\vec{\beta}) = \kappa(\vec{\beta})$$

$$\begin{aligned}\vec{\beta}'(s) &= \vec{\alpha}'(s) - (\vec{\alpha}'(s) \cdot \vec{u}_0) \vec{u}_0 \rightarrow \left(\vec{\beta}'(0) = \vec{\alpha}'(0) - (\vec{\alpha}'(0) \cdot \vec{u}_0) \vec{u}_0 \right. \\ &= \vec{T} - (\vec{T} \cdot \vec{u}_0) \vec{u}_0 \quad \left. = \vec{\alpha}'(0) = \vec{T}_0 \right.\end{aligned}$$

$$\vec{\beta}''(s) = \kappa \vec{N} - (\kappa \vec{N} \cdot \vec{u}_0) \vec{u}_0$$

$$\vec{\beta}''(0) = \kappa \vec{N} - \kappa(\vec{\alpha}') \vec{u}_0$$

$$\kappa(\vec{\beta}) = \frac{|\vec{\beta}' \times \vec{\beta}''|}{|\vec{\beta}'|^3} = \frac{|\vec{T}_0 \times (\kappa \vec{N}_0 - \kappa(\vec{\alpha}') \vec{u}_0)|}{|\vec{T}_0|^3}$$

$$= |k_\alpha \vec{N}_0 - k(\vec{x}') \vec{U}_0| \quad k_2 \vec{N}_0 = k(\vec{x}') \vec{U}_0 + k_g \vec{U}_0 \times \vec{T}_0$$

$$= |k_g \vec{U}_0 \times \vec{T}_0| = k_g \checkmark$$

(5.1.9) \vec{x} curve on S_R^2 , \vec{x} geodesic $\Leftrightarrow \vec{x}$ great circle,

(\Leftarrow) \vec{x} great circle $\Rightarrow \vec{x} \subset S_R^2 \cap P$, P plane through O
 so $P \perp S_R^2$. Have proved this gives a geodesic.

($\vec{U} \in P, \vec{U} \perp \vec{T}; \vec{N} \in P, \vec{N} \perp \vec{T} \Rightarrow \vec{N} = \pm \vec{U} \Rightarrow k_g = 0$)

(\Rightarrow) \vec{x} unit speed. \vec{x} geodesic $\Rightarrow \vec{x}'' \parallel \vec{U} \Rightarrow \vec{N} = \pm \vec{U}$
 $\vec{N} = \pm \frac{1}{R} \vec{x}$.

$$\vec{N}' = \pm \frac{1}{R} \vec{x}' \Rightarrow \kappa \vec{T} + \tau \vec{B} = \pm \frac{1}{R} \vec{T} \Rightarrow \tau = 0, \kappa = \frac{1}{R}$$

$\Rightarrow \vec{x}$ plane circle of radius R

$$\vec{B} \perp \vec{N} \Rightarrow \vec{B} \perp \vec{U} \Rightarrow \vec{B} \perp \vec{x} \quad |\vec{x}| = R$$

$\Rightarrow P$ goes through $O \Rightarrow \vec{x} \subset S_R^2 \cap P \Rightarrow \vec{x}$ great circle.

(5.1.10) \vec{x} geod. on M , $\vec{x} \subset P \Rightarrow \vec{x}$ line of curvature.

$\vec{x} \subset P \Rightarrow \tau = 0 \Rightarrow \vec{B}$ constant, $\vec{B} \perp P$

\vec{x} geodesic $\Rightarrow \vec{N} = \pm \vec{U}$, so $\vec{U}' = \pm \vec{N}' = \pm \kappa \vec{T} \pm \tau \vec{B}$

$$\vec{U}' = \pm \kappa \vec{T}$$

$$S(\vec{T}) = \pm \kappa \vec{T}$$

\vec{T} eigenvector of S

\vec{x} line of curvature.

(5.1.12) Find the geodesics on the cylinder

$$M: x^2 + y^2 = R^2$$

$$\vec{r}(u, v) = (R \cos u, R \sin u, bv)$$

$$\vec{r}(t) = (R \cos u(t), R \sin u(t), bv(t))$$

$$\vec{r}' = \left(-R \sin u \frac{du}{dt}, R \cos u \frac{du}{dt}, b \frac{dv}{dt} \right)$$

$$\vec{r}'' = \left(-R \cos u \left(\frac{du}{dt} \right)^2 - R \sin u \left(\frac{d^2u}{dt^2} \right), -R \sin u \left(\frac{du}{dt} \right)^2 + R \cos u \left(\frac{d^2u}{dt^2} \right), b \frac{d^2v}{dt^2} \right)$$

$$U = (\cos u, \sin u, 0)$$

$$\vec{r}'' = -R \left(\frac{du}{dt} \right)^2 \vec{U} + \underbrace{\left(-R \sin u \frac{d^2u}{dt^2}, +R \cos u \frac{d^2u}{dt^2}, b \frac{d^2v}{dt^2} \right)}_{=0}$$

$$\Rightarrow \frac{d^2u}{dt^2} = 0, \quad \frac{d^2v}{dt^2} = 0$$

$$\Rightarrow \frac{du}{dt} = a \quad \frac{dv}{dt} = c$$

$$\Rightarrow \frac{du}{dt} = at + b \quad \frac{dv}{dt} = ct + d$$

$$\text{So } \vec{r}(t) = \vec{r}(at+b, ct+d) \quad \checkmark$$

(5.1.13) nonsense, since the proof is false.