

Volume, degree and entropy

Benson Farb
University of Chicago

Joint work with Chris Connell

The Degree Theorem

Degree Theorem. *Let M be a closed, locally symmetric n -manifold of nonpositive curvature. Assume that M has no local direct factors isometric to \mathbb{R}^k , \mathbb{H}^2 , or $\mathrm{SL}_3(\mathbb{R})/\mathrm{SO}_3(\mathbb{R})$. Then for any closed Riemannian manifold N and continuous map $f : N \rightarrow M$,*

$$|\mathrm{deg}(f)| \leq C \frac{\mathrm{Vol}(N)}{\mathrm{Vol}(M)}$$

where C depends only on n and on the smallest Ricci curvatures of N and M .

Remarks

- Case when M negatively curved: Gromov, 1983.
- Case of surfaces M : follows from Gauss-Bonnet. (plus)
- FALSE with \mathbb{R}^k factors: the torus T^k has self-maps of any degree d .
- Dependence of C on Ricci curvatures is necessary.
- There is a finite volume version.
- **Entropy Rigidity Conjecture (Gromov):** give exact best constant C , with equality iff Riemannian covering.

Proved for M :

- negatively curved (Besson-Courtois-Gallot); settled many conjectures.
- locally (not nec. globally!) isometric to a product of negatively curved (BCG, Connell-F).

Corollary: Positivity of Minvol

Minimal volume. One of the basic invariants of a smooth manifold is the *minimal volume* of N :

$$\text{Minvol}(N) := \inf_g \{ \text{Vol}(N, g) : |K(g)| \leq 1 \}$$

Corollary 1. [Positivity of Minvol] M as in degree theorem $\implies \text{Minvol}(M) > 0$.

Compact case: proved by Savage (1982) for $M = \Gamma \backslash \text{SL}_n(\mathbb{R}) / \text{SO}_n(\mathbb{R})$ and by Gromov (1983) in general.

Open question: Compute $\text{Minvol}(M)$. Is it realized by the locally symmetric metric?

YES (even uniquely!) for real-hyperbolic M (B-C-G).

($n=2$ follows from Gauss-Bonnet)

$$K \geq -1$$

$$\int_{\Sigma} K dA = 2\pi \chi(\Sigma)$$

Corollary: Self-maps

Corollary 2. [No self-maps] M as in degree theorem $\implies M$ admits no self-maps of degree > 1 .

In particular, $\pi_1(M)$ is co-Hopfian: every injective endomorphism of $\pi_1(M)$ is surjective.

Also follows from Margulis Superrigidity. Co-Hopf property first proved by Prasad (1976).

Proof of Corollary 2: $\deg(f^n) = \deg(f)^n$. Now apply the Degree Theorem. \diamond

Proof of the Degree Theorem

Main Theorem: Any $f : N \rightarrow M$ is homotopic to a smooth map F with $\text{Jac } F \leq C$.

- Unlike harmonic maps, $D_x F$ is explicit.
- This implies the Degree Theorem since:

degree theory \implies

$$\begin{aligned} |\deg(f)| \text{Vol}(M) &= \int_N |F^* dg_M| \\ &= \int_N |F^* dg_M| \\ &\leq \int_N |\text{Jac } F| dg_N \\ &\leq C \text{Vol}(N) \end{aligned}$$

Constructing the remarkable map F

(after Douady-Earle and B-C-G)

Lift $f : N \rightarrow M$ to $\tilde{f} : Y \rightarrow X$. Today: assume $K(Y) \leq 0$ (VERY SPECIAL!)


To construct $\tilde{F} : Y \rightarrow X$ we:

Step 1: Find a natural family of probability measures ν_y parameterized by $y \in Y$.

Step 2: Find a natural map $\partial\tilde{f} : \partial_\infty Y \rightarrow \partial_\infty X$.

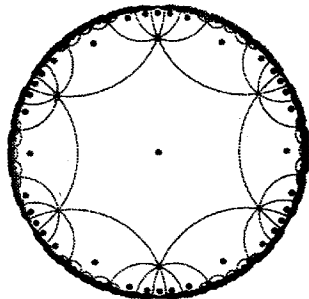
Step 3: Take the *barycenter* of a probability measure on $\partial_\infty X$, giving a map $\text{bar} : \mathcal{M}_1(\partial_\infty X) \rightarrow X$.

Then define \tilde{F} by:

$$\begin{array}{ccc}
 \mathcal{M}_1(\partial_\infty Y) & \xrightarrow{(\partial\tilde{f})_*} & \mathcal{M}_1(\partial_\infty X) \\
 \uparrow & & \downarrow \text{bar} \\
 Y & \xrightarrow{\tilde{F}} & X
 \end{array}$$


Step 1: Patterson-Sullivan Measures

Density of $\Gamma \cdot p$ at infinity as viewed from $y \in Y$ gives Patterson-Sullivan measure ν_y on $\partial_\infty Y$.



Key Properties of Patterson-Sullivan Measures ν_x :

1. Equivariance: $\nu_{\gamma x} = \gamma_* \nu_x$
2. Explicit Radon-Nikodym derivative $\frac{d\nu_y}{d\nu_x}$
3. (Knieper, Albuquerque) Each ν_x is supported on a specific Γ -orbit in $\partial_\infty Y$.

C. Albuquerque
OF

Step 2: Constructing the map

$$\partial \tilde{f} : \partial_\infty Y \rightarrow \partial_\infty X$$

Morally:

1. By nonpositive curvature, Y and X have "visual compactifications" $\partial_\infty Y$ and $\partial_\infty X$.
2. Extend $\tilde{f} : Y \rightarrow X$ to these compactifications using coarse geometry (where do geodesic rays go?).

Warning: Can't really do this!

Step 3: Barycenter Functional

Busemann functions: Pick basepoint $p \in X$. For $x \in X$, $\theta \in \partial_\infty X$,

$$B(x, \theta) = \lim_{z \rightarrow \theta} d(x, z) - d(p, z)$$

Convex Functional:

$$B : X \times \mathcal{M}_1(\partial_\infty X) \rightarrow \mathbb{R}$$

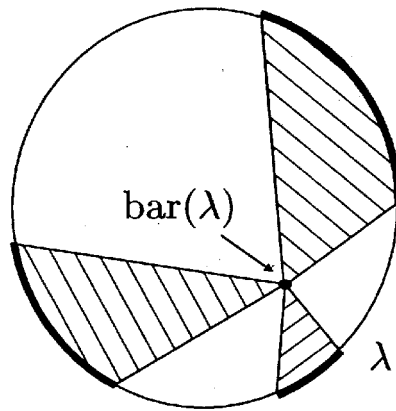
$$B(x, \lambda) = \int_{\partial_\infty X} B(x, \theta) d\lambda(\theta)$$

Key fact: $B(\cdot, \lambda)$ strictly convex.

Step 3: Barycenter map and F

$$\text{bar} : \mathcal{M}_1(\partial_\infty X) \rightarrow X$$

$$\text{bar}(\lambda) := \text{unique critical point of } \mathcal{B}(\cdot, \lambda)$$



Now define \tilde{F} by

$$\tilde{F}(x) := \text{bar}((\partial \tilde{f})_* \nu_x)$$

Estimating |Jac F|

Let $\sigma_y = (\partial \tilde{f})_* \nu_y$. Now F is defined by the implicit vector equation:

$$\int_{\partial_\infty X} dB_{(F(y), \theta)}(\cdot) d\sigma_y(\theta) = 0$$

Differentiating, taking det, making estimates, rearranging, etc. gives:

$$\text{Jac } F \leq C \frac{\det \left(\int_{\partial_\infty X} dB(\cdot)^2 d\sigma_y(\theta) \right)^{1/2}}{\det \left(\int_{\partial_\infty X} DdB(\cdot, \cdot) d\sigma_y(\theta) \right)}$$

Key fact: Can replace $\partial_\infty X$ by maximal compact $K \subset G = \text{Isom}(X)$.

Same estimate as B-C-G.
In hyperbolic cases, a miracle occurs: can write bottom in terms of top.

Convert to a Lie groups problem

Now combine:

- Eigenvalue estimates on DdB
- For M_i positive semidefinite, $\det(\sum M_i)$ is a nondecreasing homogeneous polynomial in eigenvalues of the M_i .

to obtain

$$|\text{Jac } F| \leq C \frac{\left(\det \int_K O_\theta \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} O_\theta^* d\sigma_y(\theta) \right)^{\frac{1}{2}}}{\det \int_K O_\theta \begin{pmatrix} 0 & 0 \\ 0 & I \end{pmatrix} O_\theta^* d\sigma_y(\theta)}$$

where I is the identity matrix of size $n - \text{rank}(X)$ and O_θ is an element of K .

It remains to bound the right hand ratio.

Eigenvalue Matching

Idea: For each small eigenvalue in the denominator, find two comparably small eigenvalues in the numerator.

Hard part: Make "comparably small" independent of the measure $(\partial \tilde{f})_* \nu_y$.

Involves: Detailed analysis of action of maximal compact K on subspaces of Lie algebra of $G = \text{Isom}(X)$ (a simple Lie group). Use:

- kernel (numerator) \supseteq cokernel (denominator): \bullet
- must find K -invariant subspace perpendicular to K -orbit of a flat, and of TWICE dimension of flat ($=\text{rank}(X)$). THIS USES $G \neq \text{SL}(3, \mathbb{R})$!

Open problems

1. Entropy Rigidity Conjecture
2. Computing Minvol
3. Degree theorems for manifolds which are not locally symmetric. [For nonpositively curved manifolds with negative Ricci curvature?]
4. Real convex projective structures on surfaces
5. Homotopy Hyperbolic Theorem
6. Positivity of Gromov Norm for nonps. curved, locally sym mflds with no torus factors.